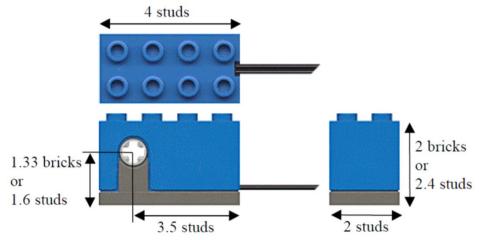


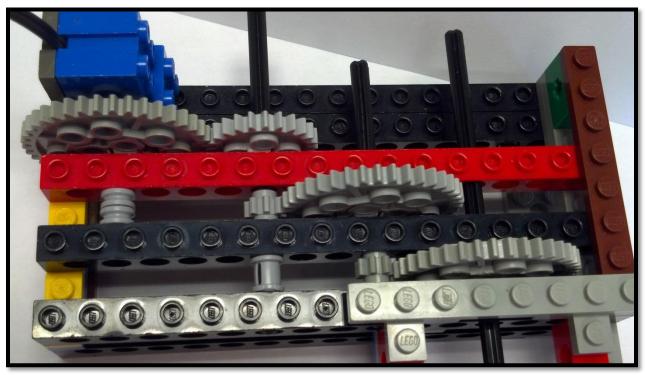
# **Rotation Sensor Model for Encoder Math Experiment**

#### **Dimension of Rotation Sensor by unit measurement**

Note: this sensor gives 16 clicks for one full revolution.

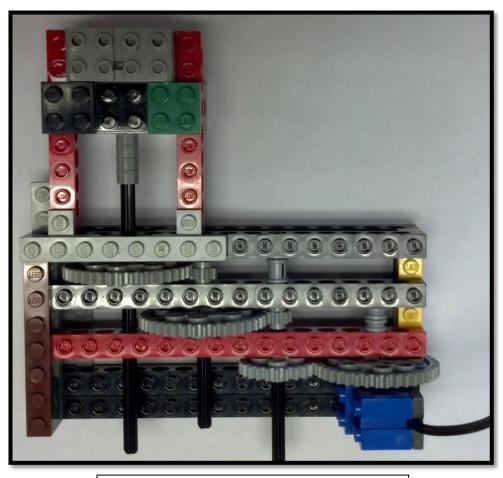


## **Top View -1**



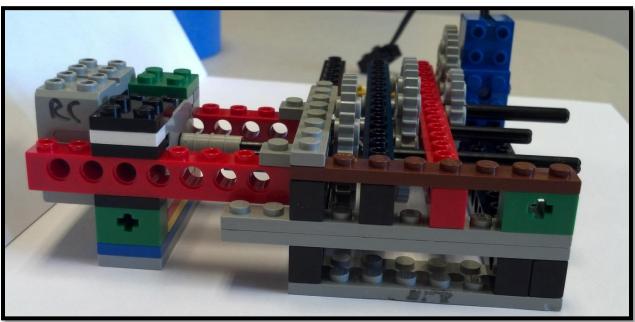


# **Top View - 2**



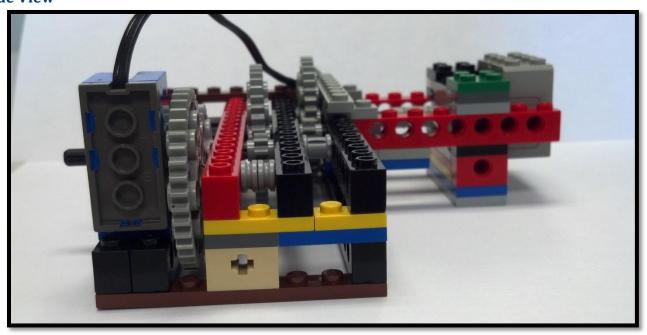
1:1 1:5 1:25 1:15

# **Long Side View**

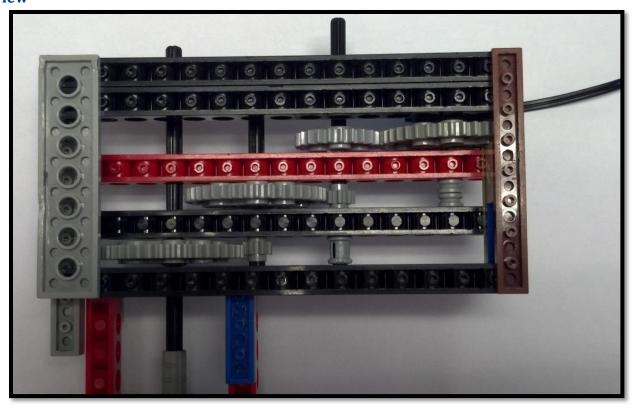




### **Short Side View**

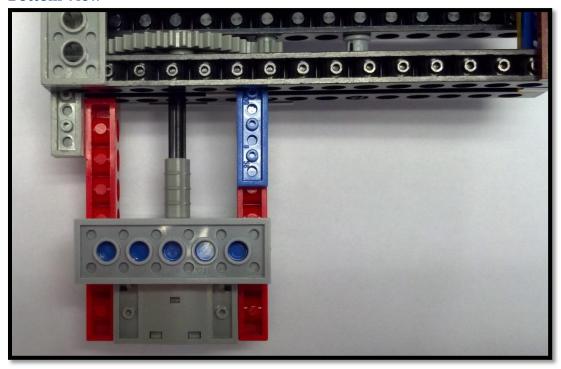


### **Bottom View**

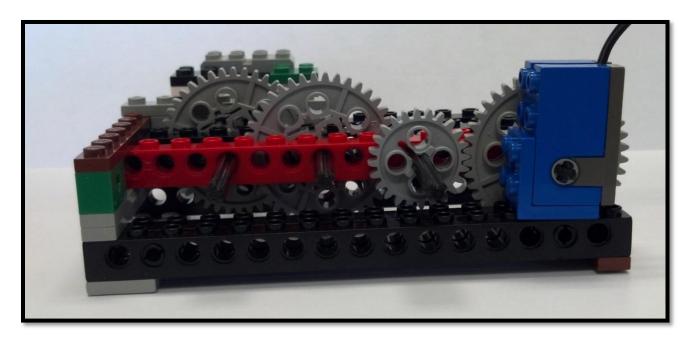




#### **Motor Mount - Bottom View**

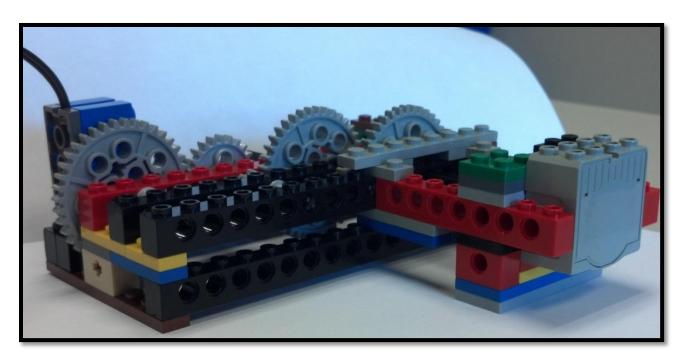


### **Rotation Sensor Mount - Side View**





### **Diagonal View**



## **One Mounting Application Sample**

Note: If a wheel attach to here:

1 wheel full revolution = rotation sensor turns 24 times.

= 24x16 clicks = 384 clicks

