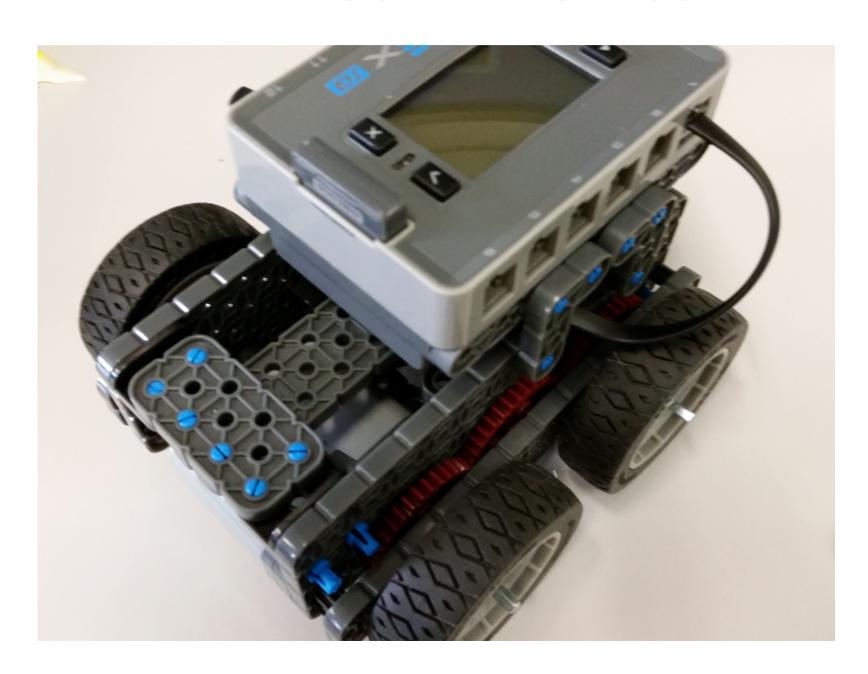
# **4 Wheel Drive Bot**



#### **Part 1: Creating the Drive Train**



Create two identical pieces which look like this.



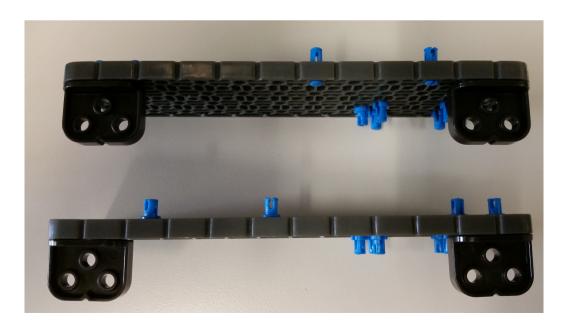


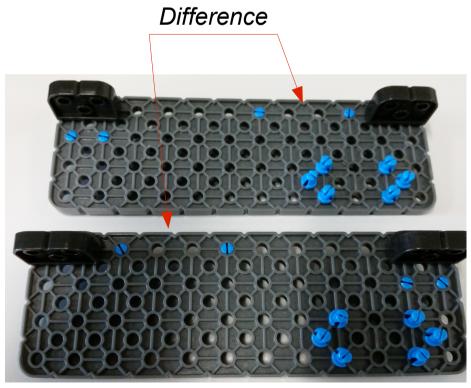


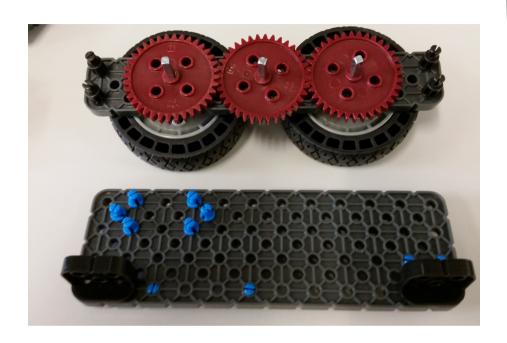
### **Part 2: Mounting the Drive Train**



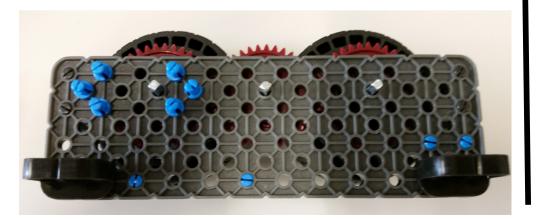
Create two of these pieces. They are not identical.



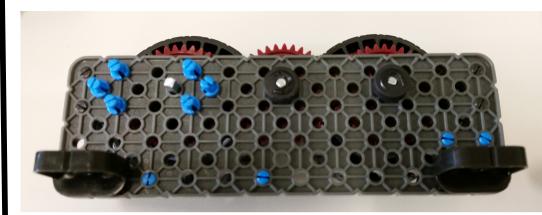




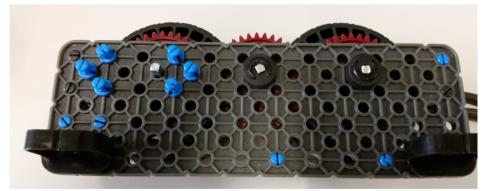
Prepare this parts and connect them like so



Put bushings on only these two axles.



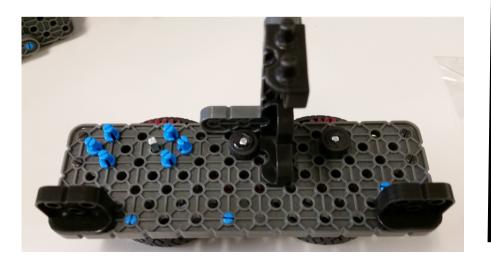
Do the same for the other set of pieces.



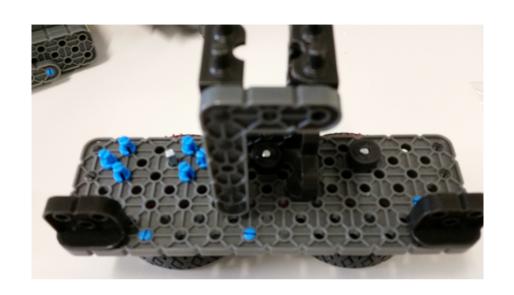
**Part 3: Connecting the Sides** 



Create these two parts and attach one like so.



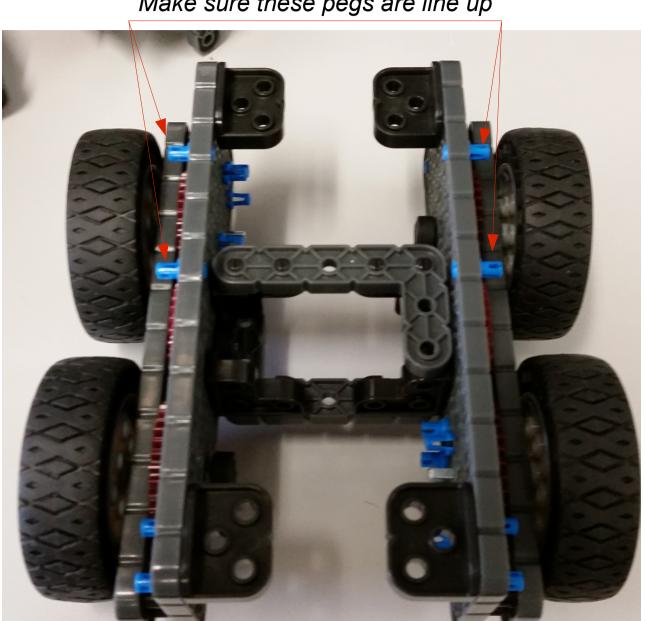
Attach the other like so.



Top View



Attach the other side like so.



Make sure these pegs are line up

### **Part 4: Bracing the Chassis**





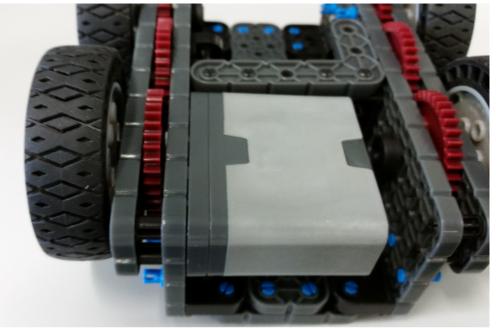
Create the following piece and attach it like so.

**Part 5: Attaching the Motors** 



Attach the motor to the designated pegs







Make sure the motor is secure and attach the other side.

### Part 5: Attaching the VEX-IQ



Attach 4 L-Brackets to the VEX-IQ



Secure it to the chassis like so.



## **Robot Complete**

